Knowledge Integration Into Language Models: A Random Forest Approach

Yi Su

Dissertation Defense

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Outline



- 2 Basic Language Models
- 3 Random Forest Language Models
 - 4 Knowledge Integration with RFLMs
- Exploiting Prosodic Breaks in LMs
 - Introduction
 - Prosodic Language Models
 - Experimental Results

Conclusions

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Introduction

- Basic Language Models
- 8 Random Forest Language Models
- 4 Knowledge Integration with RFLMs
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6 Conclusions

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What Is A Language Model?

- How likely will a sentence be uttered by a human?
- Complete the sentence:

Wouldn't it be ...

- ... great?
- ... awesome?
- ... lovely?
- o ... loverly!

Lots of choc'lates for me to eat, Lots of coal makin' lots of 'eat. Warm face, warm 'ands, warm feet Aow, wouldn't it be loverly?

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State of the Art

- *N*-gram language models remain the *de facto* standard
 - Ignore the fact that we are modeling human language
- But we know so much more about language!
 - give, gave, given (morphology)
 - love (verb), lover (noun), lovely (adjective) (part-of-speech)
 - this:is::these:are (agreement)
 - . . .
- Even machines "know" something
 - Morphological analyzers
 - Part-Of-Speech (POS) taggers
 - Parsers
 - ...

Putting language into language modeling (Jelinek and Chelba, 1999)

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Language Models (LMs)

- A probability distribution over all possible word sequences P(W), where $W = w_1 \dots w_N \in V^*$, *V* is the vocabulary.
- Decompose using the chain rule

$$P(W) = \prod_{i=1}^{N} P(w_i \mid w_1, \dots, w_{i-1}) \approx \prod_{i=1}^{N} P(w_i \mid \Phi(w_1, \dots, w_{i-1})),$$

where $\Phi: V^* \mapsto C$ is an equivalence mapping of histories.

• An important component in speech recognition, machine translation and information retrieval system.

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Decision Tree Language Models

- Language modeling as equivalence mapping of histories
- N-gram language models
 - Markovian assumption

$$P(w \mid h) \approx P(w \mid \Phi(h)) = P(w \mid w_{i-n+1}^{i-1}),$$

where $h = w_1, \ldots, w_{i-1} = w_1^{i-1}$.

- Decision tree language models (Bahl et al., 1989)
 - Decision tree classifier as equivalence mapping

 $P(w \mid h) \approx P(w \mid \Phi(h)) = P(w \mid \Phi_{DT}(h)).$

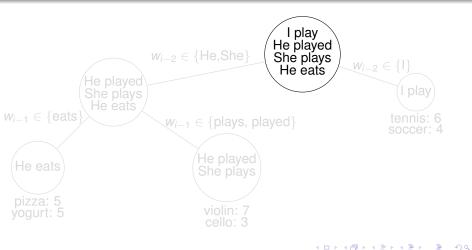
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Decision Tree Training

- Growing (Top-down)
 - Start from the root node, which contains all *n*-gram histories in the training text;
 - Recursively split every node to increase the likelihood of the training text by an exchange algorithm (Martin, Liermann and Ney, 1998);
 - Until splitting can no longer increase the likelihood.
- Pruning (Bottom-up)
 - Define the potential of a node as the gain in heldout text likelihood by growing it into a sub-tree
 - Prune away nodes whose potentials fall below a threshold.

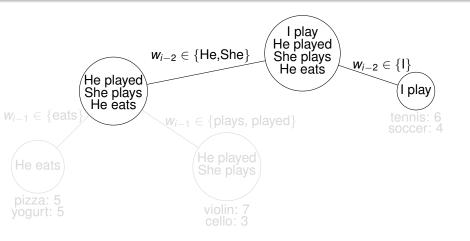
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Decision Tree Language Models: Training



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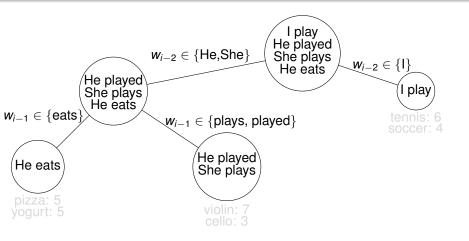
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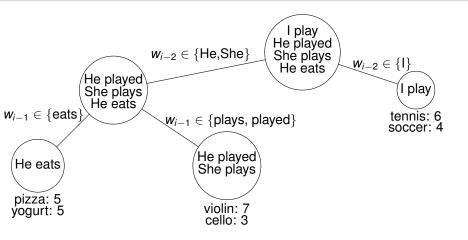
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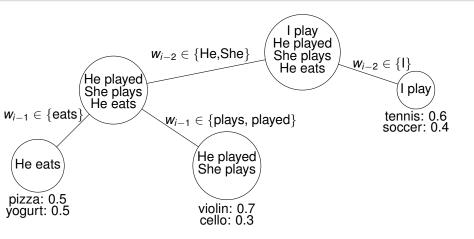
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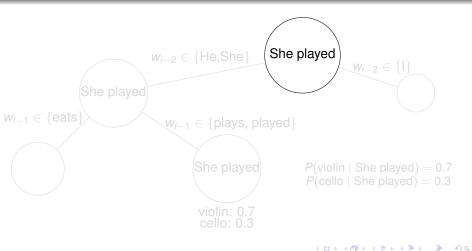


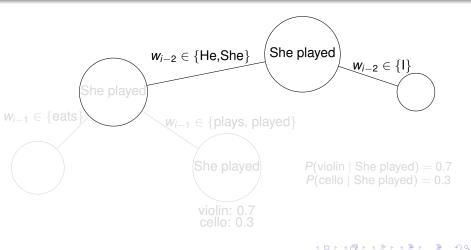
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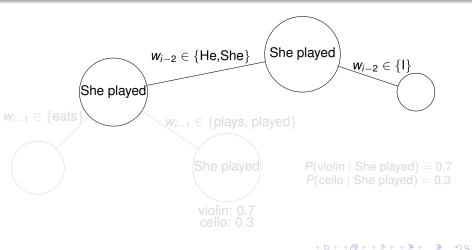
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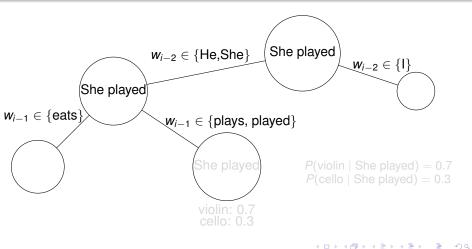


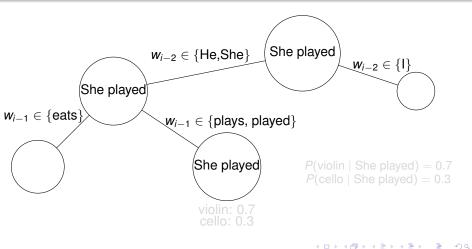
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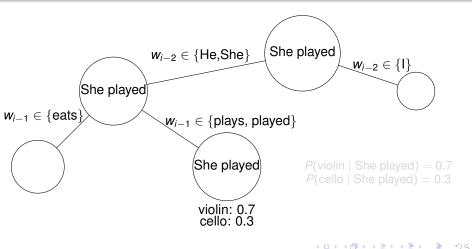




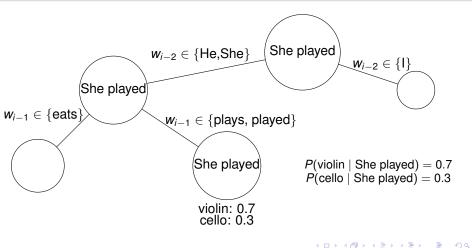








Decision Tree Language Models: Testing



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Decision Tree Language Models

- Failed to improve upon *n*-gram language models (Potamianos and Jelinek, 1998)
 - Without efficient search algorithm, greedy tree building can't find a good tree
 - Failed to control the variance
- Random forest (Breiman, 2001)
 - A collection of randomized decision trees
 - Reach final decision by voting to reduce variance

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Good results in many classification tasks

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Outline

3

Random Forest Language Models Introduction Prosodic Language Models

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Random Forest Language Models (RFLMs)

- A collection of randomized decision tree language models or an i.i.d. sample of decision trees (Xu and Jelinek, 2004)
- Probability via averaging

$$P(w \mid h) = \frac{1}{M} \sum_{j=1}^{M} P(w \mid \Phi_{DT_j}(h))$$

 Superior to n-gram language model in terms of perplexity and word error rate on small size corpora (Xu and Mangu, 2005)

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Training Randomization

- Random initialization of the exchange algorithm
 - Combat local maximum problem caused by greediness of the exchange algorithm (Martin, Liermann and Ney, 1998)
- Random selection of questions
 - Set membership of a word in a history position j

$$q_S^j(w_1^{i-1}) = \left\{ egin{array}{cc} 1 & ext{, if } w_j \in S; \\ 0 & ext{, otherwise} \end{array}
ight.$$

where $1 \leq j \leq i - 1$ and $S \subset V$.

- Randomly choose a subset of history positions to investigate
- Random sampling of the training data

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Smoothing RFLM

Kneser-Ney-style smoothing

$$P(w_i \mid w_{i-n+1}^{i-1}) = \frac{\max(C(w_i, \Phi(w_{i-n+1}^{i-1})) - D, 0)}{C(\Phi(w_{i-n+1}^{i-1}))} + \lambda(\Phi(w_{i-n+1}^{i-1}))P_{KN}(w_i \mid w_{i-n+2}^{i-1})$$

- Can be improved by modified Kneser-Ney smoothing (Chen and Goodman, 1999)
 - Used in all experiments henceforth.

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Why N-gram LMs Work

"There is no data like more data." — Robert L. Mercer

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- Performance of a statistical model depends on the amount of training data
- Simplicity implies scalability
 - N-gram LMs outperform complex LMs by using more data

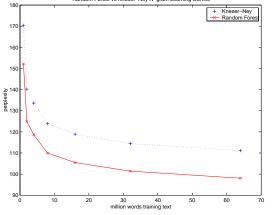
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Large-Scale Training and Testing

- Problem: straightforward implementation quickly uses up addressable space.
 - Memory requirement grows as tree grows
- Solution: an efficient disk swapping algorithm exploiting
 - Recursive structure of binary decision tree
 - Compact representation for fast reading and writing
 - Local access property of tree-growing algorithm
 - Node-splitting depends only on the data it contains
- Achieve I/O overhead linear to the size of training *n*-gram types (Su, Jelinek and Khudanpur, 2007).

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Learning Curves



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Random Forest vs Kneser-Ney N-gram Learning Curves

Knowledge Integration Into LMs

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Automatic Speech Recognition (ASR)

- System: IBM GALE Mandarin ASR
- Vocabulary: 106K words
- Data: 100M * 7 = 700M words for training, 10M for held-out, 20k for testing

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• Parameters: 4-grams, 50 trees per forest

Table: Lattice rescoring for IBM GALE Mandarin ASR

Character Error Rate (%)	All	BN	BC
Baseline	18.9	14.2	24.8
RFLM	18.3	13.4	24.4

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Outline

4

Knowledge Integration with RFLMs Introduction Prosodic Language Models

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Knowledge Integration

- RFLM as a framework for integrating linguistic knowledge
 - Decision tree can ask any question about the history
- Feature: a function *f*(*h*) that maps *h* to an element of a finite set.

$$f: V^* \mapsto E,$$

where V is the vocabulary, E is the set of feature values.

• Question: the indicator function $q_S^f(h)$ of the set $f^{-1}(S) = \{h : f(h) \in S \subset E\}.$

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$$q^{f}_{\mathcal{S}}(h) = \left\{ egin{array}{cc} 1 & ext{, if } f(h) \in \mathcal{S} \subset E; \\ 0 & ext{, otherwise.} \end{array}
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Feature Engineering

• Features we have used so far:

• Word features: if $h_i = w_1 \cdots w_{i-1}$, then

 $WORD_j(h_i) \doteq w_{i-j},$

- Features we can potentially use:
 - Any discrete-valued function on the history!
 - E.g., Part-Of-Speech (POS) features: POS_j(h_i) ≐ r_{i−j}, where r_{i−j} is the POS tag of the word w_{i−j}, as provided by an incremental POS tagger.
 - Feature vector representation of a history h

$$F(h) \doteq (f_0(h), f_1(h), \cdots, f_k(h)).$$

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Introduction Prosodic Language Model Experimental Results

Outline

Exploiting Prosodic Breaks in LMs 5 Introduction Prosodic Language Models Experimental Results

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Introduction Prosodic Language Models Experimental Results

What Is Prosody?

- Suprasegmental properties of spoken language units
- A wide range: tone, intonation, stress, break, etc.
- Many applications
 - Disfluency & sentence boundary detection (Stolcke et al, 1998)
 - Topic segmentation (Hirschberg and Nakatani, 1998)

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- Spoken language parsing (Hale et al, 2006)
- • •
- We are interested in using prosodic breaks for language modeling.

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Introduction Prosodic Language Models Experimental Results

What Is A Prosodic Break Index?

- Number representing subjective strength of one word's association with the next
- On a scale from 0 (the strongest conjoining) to 4 (the most disjoining)
- Example:

Time flies like an arrow.

Time/3 flies/2 like/1 an/0 arrow/4. Time/1 flies/3 like/2 an/0 arrow/4.

- Prosodic breaks help resolve syntactic ambiguity (Dreyer and Shafran, 2007)
- We think they should help resolve lexical ambiguity, too.

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Introduction Prosodic Language Models Experimental Results

Speech Recognition with Side Information

• Proposal 1: If S is hidden, then

$$W^* = \underset{W}{\operatorname{arg\,max}} P(W \mid A) = \underset{W}{\operatorname{arg\,max}} P(A \mid W) \sum_{S} P(W, S).$$

Proposal 2: If S is observable, then

 $(W, S)^* = \underset{W,S}{\operatorname{arg\,max}} P(W, S \mid A) \approx \underset{W,S}{\operatorname{arg\,max}} P(A \mid W) P(W, S).$

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Introduction Prosodic Language Models Experimental Results

Are Prosodic Breaks Hidden or Observable?

- Strictly speaking, only acoustic features are observable in speech recognition;
- However, unlike hidden structures such as parse trees, prosodic breaks can be predicted from acoustic features with high precision. (Hale et al, 2006)
 - 83.12% for predicting a 3-valued break on annotated Switchboard
- Each case has its pros and cons.
- We are going to investigate these two options for the purpose of language modeling.

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Introduction Prosodic Language Models Experimental Results

Joint Model of Words and Breaks

$$P(W, S) \approx \prod_{i=0}^{m} P(w_i, s_i \mid w_{i-n+1}^{i-1}, s_{i-n+1}^{i-1})$$

• Tuple Model: Let $t_i = (w_i, s_i)$, for all $0 \le i \le m$. We have

$$P(w_i, s_i \mid w_{i-n+1}^{i-1}, s_{i-n+1}^{i-1}) = P(t_i \mid t_{i-n+1}^{i-1}).$$

Decomposed Model

$$P(w_i, s_i \mid w_{i-n+1}^{i-1}, s_{i-n+1}^{i-1}) = P(w_i \mid w_{i-n+1}^{i-1}, s_{i-n+1}^{i-1}) P(s_i \mid w_{i-n+1}^{i}, s_{i-n+1}^{i-1})$$

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Introduction Prosodic Language Models Experimental Results

One Problem

$$P(s_i \mid w_{i-n+1}^i, s_{i-n+1}^{i-1}) =?$$

- How do we smooth things like this? Back-off! Deleted interpolation!
- In what order do we back off or delete? Well...
 - No "natural order" of backing off
 - Previous research either relied on heuristics (Chelba and Jelinek, 2000; Charniak, 2001)
 - Or tried to find the "optimal" path or combination of paths (Bilmes and Kirchhoff, 2003; Duh and Kirchhoff, 2004)
- We have something better... Random Forests!

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Introduction Prosodic Language Models Experimental Results

Ask the Right Question

- Questions
 - We have asked:

Is the word w_{i-1} in the set of words $\{a, an, the\}$?

We would like to ask:

Does the prosodic break s_{i-1} take its value in the set of values {1,2,3}?

- Same algorithms for training and testing
- Natural integration with background n-gram LM

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• Feature selection on-the-fly!

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Introduction Prosodic Language Models Experimental Results

Experimental Setup

- Vocabulary: 10k
- Data: ToBI-labeled Switchboard (Ostendorf et al., 2001).
 - 666k words for training
 - 51k words for held-out
 - 49k words for testing
- Parameters:
 - history up to 2 words and 2 breaks ("3-grams")

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100 trees per forest

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Introduction Prosodic Language Models Experimental Results

Granularity

- Granularity of prosodic breaks might be too coarse for LM
- Compared 2-, 3- and 12-valued scheme for

$$P(w_i | w_{i-1}, w_{i-2}, s_{i-1}, s_{i-2})$$

Table: Granularity of Prosodic Breaks

Model	two-level	three-level	contvalued
KN.3gm	66.1	66.1	66.1
RF-100	65.5	65.4	56.2

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Introduction Prosodic Language Models Experimental Results

Main Results

Table: Main Perplexity Results

Model	Method	KN	RF
<i>P</i> (<i>W</i> , <i>S</i>)	tuple 3gm	358	306
	decomp.	274	251
P(W)	tuple 3gm	69.3	67.2
$=\sum_{S} P(W,S)$	decomp.	66.8	64.2
P(W)	word 3gm	66.1	62.3

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3

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3

Outline

Introduction

- 2 Basic Language Models
- 3 Random Forest Language Models
- 4 Knowledge Integration with RFLMs
- 5 Exploiting Prosodic Breaks in LMs
 - Introduction
 - Prosodic Language Models
 - Experimental Results

6 Conclusions

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Conclusions

• Random forest language model as a general framework

- For integrating knowledge into language models
- Exploiting prosodic breaks in language modeling with random forests (Su and Jelinek, 2008)
 - Finer grained prosodic break indices are needed.

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• Prosodic breaks should be given to language models.

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